CSC 471 midterm 1 – Spring 2017

Name:_____

READ ME FIRST

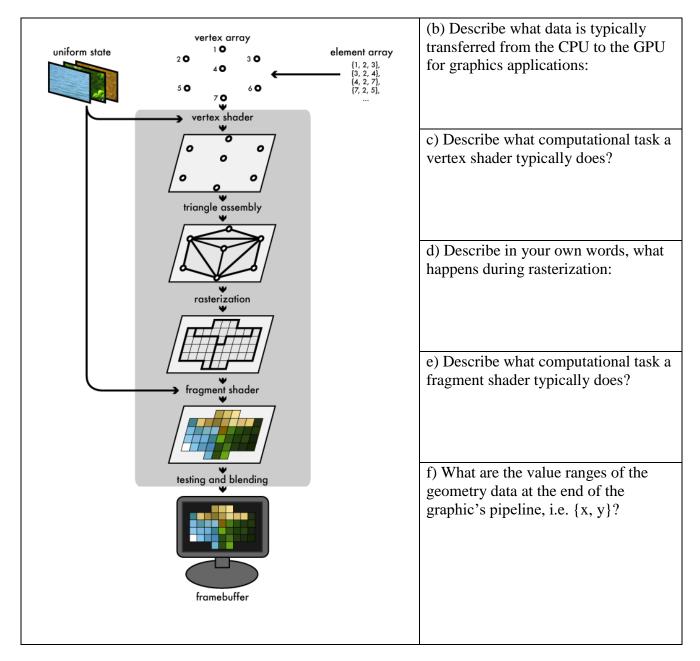
- Work individually! You may use a calculator
- Don't spend too much time on any one problem. This exam should take 80 minutes.
- Be neat
- Show how you got your answers!
- When in doubt, write down your assumptions
- You are allowed to use a calculator

1	15 pts	Short answer	
2	10 pts	Vectors	
extra credit	2 pts		
3	30 pts	2D transform matrices	
4	15 pts	Transforms	
5	20 pts	More Transforms	
6	10 pts	Rasterization	
	100 pts	Grand total	

1) Short answer/ true & false questions (20 pts)

a) (1 pt) In a very general sense, the GPU can be viewed as a SIMD machine that allows a program to run the same 'vertex shader' program on multiple different vertices in parallel and then run a 'fragment shader' program on multiple fragments in parallel, thus speeding up the process of rendering computer graphics
 True False

(b-f) Refer to the following figure and fill in the missing information – short answers (2 pts each):



g) (4 pts) Assume in your game the circle defined by:

 $f(x, y) = (x - x_c)^2 + (y - y_c)^2 - r^2$

with $\{xc, yc\} = \{-1, 5\}$ and a radius of 2.5, is shielded from the highly contagious zombie virus. If you place your trusty steed at point $\{1, 6\}$ are they safe from contamination? (show your work with math):

2) Vectors (10 pts)

Given the following vectors: $\mathbf{v}^{\mathrm{T}} = [7, 9, 3]$ and $\mathbf{u}^{\mathrm{T}} = [7, 11, 3]$ Compute: 1) (2 pts) v+u=

- 2) (2 pts) $v \cdot u =$
- 3) (2 pts) If w = v-u, What is the length of the vector w?
- 4) (4 pts) Write the normalized form of w (from the part 3) (i.e. write w as a unit length vector).
- 5) (2 pt extra credit): draw the vector -1*w (accurately depicting length (ratio) and direction) as some part of a creature (make it clear which part of the creature is the vector) you may define the units (i.e. inches, feet, etc.)

3) 2D transform matrices (30 pts)

Given the following 2D transform matrices:

$$m_{0} = \begin{bmatrix} .707 & -.707 & 0 \\ .707 & .707 & 0 \\ 0 & 0 & 1 \end{bmatrix} m_{1} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{bmatrix} m_{2} = \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & -2 \\ 0 & 0 & 1 \end{bmatrix} m_{3} = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

a) Name what type of 2D transformation is associated with each matrix and say something about the magnitude of the transform for x or y. (4 pts total) m0:

m1:

m2:

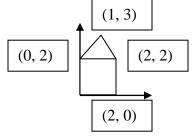
m3:

b) If these are 2D transforms, why are they 3x3 matrices? (Write 1-2 sentences) (2 pts)

c) Carefully compute m0*m2 (that is write out the composite matrix) (4 pts):

d))(13 pts total)

(4 pts) **Draw** the result of applying the composite matrix (from part (c) – i.e. m0*m2) to the following figure (draw the entire house transformed). (3 pts each) **Include** coordinate labels for your completed drawing for the updated points {0, 2}, {1, 3} and {2, 2} (Be careful about how you represent the 2D points as vectors of length 3



- (3 pts) {0, 2} :
- (3 pts) {1,3}:
- (3 pts) {2, 2} :

e) Now, only **draw** the result of applying two transforms: m1*m3 to the same figure (feel free to compute the composite matrix if that helps you, but it is not required). Be sure that your drawing includes a representation of the axes to clarify the house' exact final position: (**7 pts**)

4) Transforms (15 pts)

Assuming you have the following functions: mat4 scale(float sx, float sy, float sz) {... } : returns a scale matrix mat4 rotate(float angle, float ax, float ay, float ax) {...} : returns a rotation matrix by the given angle and axis [ax, ay, az]

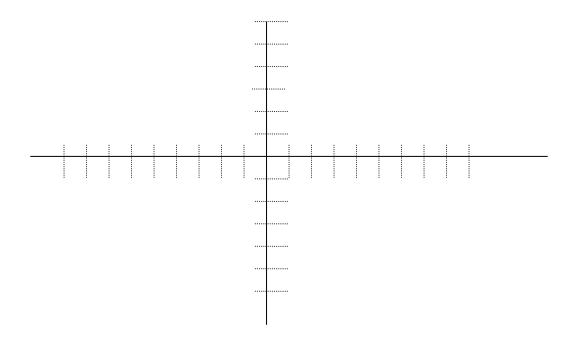
mat4 translate(float tx, float ty, float tz) {...} : returns a translation matrix And assume the operator * is defined for matrix multiplication as expected Carefully draw the result of the following OpenGL/GLSL code assuming that the DrawRobotFace() function draws the complete image below (i.e. one grey box with sides of length 2 with three small sub-boxes inside with sides of length 0.5: white eyes and a

black mouth). Recall that rotations are specified as counter-clockwise. <u>Carefully read</u> all the code below before drawing and be sure that it is clear what the final drawing will

look like (a mat4 is a GLSL/glm 4x4 matrix – as expected):

	(1.0,1.0,0.0)
(-1.0,-1.0,0.0)	<pre>/*Set up the first matrix */ mat4 Scale = scale(2, 1, 1); mat4 Trans = translate(-2, 0, 0); mat4 Rot = rotate(-45, 0, 0, 1); mat4 Model = Trans*Rot*Scale; /*send matrix to the vertex shader */ glUniformMatrix4fv(prog->getUniform("MV"), 1, GL_FALSE, Model); /* Draw */ DrawRobotFace (); /*Set up the second matrix */ mat4 Scale = scale(1, 1, 1); mat4 Trans = translate(1, 1, 0); mat4 Rot = rotate(45, 0, 0, 1); mat4 Model = Trans*Rot*Scale; /*send matrix to the vertex shader */ glUniformMatrix4fv(prog->getUniform("MV"), 1, GL_FALSE, Model); /* Draw */ DrawRobotFace (); /* Draw */ DrawRobotFace (); /* Draw */ DrawRobotFace ();</pre>

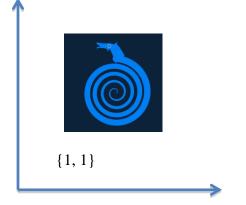
Complete your drawing on the next page



5) More Transforms (20 pts) – please write neatly

Assuming that the DrawDragon() function draws the image below, that by default draws in a bounding box that ranges from a lower left corner of $\{1,1\}$ and extends to an upper right corner of $\{2,2\}$. Recall that rotations are specified as counter-clockwise. Write transform code, using a similar coding convention to what is used in question 4 that will result an animated scene (assume your code is within a loop – no need to write the loop). The scene should include two dragons centered at $\{-1, 0\}$ and $\{1, 0\}$ each facing away from one another and each spinning around its center (the one on the right in a clockwise direction, with the one on the left spinning in a counter clockwise direction). Example frames from an implementation are included below for clarity.

Default draw position of the DrawDragon() – carefully note the dragon's default position in space:



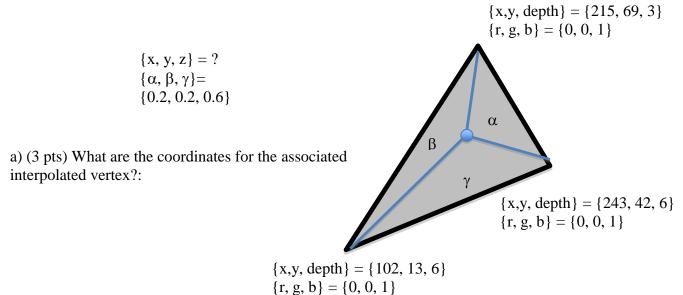
1) The start of the scene – note the white	2) As time proceeds both dragons rotate in	
lines represent the x and y axis	opposite directions (around their own	
	center)	
3) And continues to rotate	4) And continues to rotate	

Write any initialization code here:

Write looped code here:

6) Rasterization (10 pts total):

If you have a triangle converted to window coordinates with the following coordinates, (including depths and colors) – **given the associated Barycentric coordinates** (ie do not compute them, use what is given):



b) (3 pts) What is the interpolated color?:

d) (4 pts) Assuming the current value stored in the depth buffer/z-buffer for the associated pixel is 5.5, would the frame buffer/color buffer be updated with the new color? Assuming the z values specified are distances measured from the camera – thus smaller values are closer to the camera.